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Plan of this class

- compiling programs
- list processing
- pattern-matching
- new data types
- labeling algorithm





List processing

```
# let rec length x = match x with
 | [ ] -> 0
 | a :: x' -> 1 + length x' ;;
   val length : 'a list -> int = <fun>
# let rec concat x y = match x with
 | [ ] -> y
  | a :: x' -> a :: concat x' y ;;
   val concat : 'a list -> 'a list -> 'a list = <fun>
# let rec reverse x = match x with
 |[]->[]
  | a :: x' -> concat (reverse x') [a] ;;
   val reverse : 'a list -> 'a list = <fun>
# let rec insert a n x =
   if n = 0 then a :: x else match x with
    |[]->[]
    | b :: x' -> b :: insert a (n-1) x' ;;
     val insert : 'a -> int -> 'a list -> 'a list = <fun>
```

List processing

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# let rec concat x y = match x with
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     val insert : 'a -> int -> 'a list -> 'a list = <fun>
```

polymorphic types

• 'a list (say ``alpha list") is type of list of any type, e.g. int list, bool list, ...

Exercices on lists

Exercices on lists

- Arbitrary precision numbers can be implemented by lists (little endian or big endian style). Write addition and multiplication algorithms.
- Conway sequence of lists starts with list [1]. Then next list in sequence is obtainte by reading previous list. Therefore [1; 1], [2; 1], [1; 2; 1; 1], [1; 1; 1; 2; 2; 1].... Print lists of Conway sequence. Is there any unlucky number ?

- products
- # let move (x, y) (dx, dy) = (x + dx, y + dy);;
- # move (2.1, 3.0) (0.5, 0.5);;
- # let dotProduct (x, y) (x', y') = (x *. x' +. y *. y');;
- # let crossProduct (x, y) (x', y') = (x *. y' -. x *. y');;

New data types

• products

let move (x, y) (dx, dy) = (x +. dx, y +. dy);; val move : float * float -> float * float -> float * float = <fun> # move (2.1, 3.0) (0.5, 0.5);; - : float * float = (2.6, 3.5) # let dotProduct (x, y) (x', y') = (x *. x' +. y *. y');; val dotProduct : float * float -> float * float -> float = <fun> # let crossProduct (x, y) (x', y') = (x *. y' -. x *. y');; val crossProduct : float * 'a -> 'b * float -> float = <fun>

```
• sums
```

```
# type complex = Cartesian of float * float | Polar of float * float ;;
# let polar_of_cartesian c = match c with
| Cartesian (x, y) -> Polar (sqrt(x *. x +. y *. y), atan (y /. x))
| Polar (rho, theta) -> c ;;
# let cartesian_of_polar c = match c with
| Polar (rho, theta) -> Cartesian (rho *. (cos theta), rho *. (sin theta))
| _ -> c ;;
# let add c c' =
let c1 = cartesian_of_polar c and c1' = cartesian_of_polar c' in
match c1, c1' with
| Cartesian(x, y), Cartesian(x', y') -> Cartesian(x +. x', y +. y')
| _ -> failwith "Impossible" ;;
```

New data types

```
• sums
```

```
# type complex = Cartesian of float * float | Polar of float * float ;;
type complex = Cartesian of float * float | Polar of float * float
# let polar_of_cartesian c = match c with
  | Cartesian (x, y) -> Polar (sqrt(x *. x +. y *. y), atan (y /. x))
  | Polar (rho, theta) \rightarrow c ;;
    val polar_of_cartesian : complex -> complex = <fun>
# let cartesian_of_polar c = match c with
  | Polar (rho, theta) -> Cartesian (rho *. (cos theta), rho *. (sin theta))
  | _ -> c ;;
    val cartesian_of_polar : complex -> complex = <fun>
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    let c1 = cartesian_of_polar c and c1' = cartesian_of_polar c' in
    match c1, c1' with
     | Cartesian(x, y), Cartesian(x', y') -> Cartesian(x +. x', y +. y')
     | _ -> failwith "Impossible" ;;
       val add : complex -> complex -> complex = <fun>
```

• recursive types
type tree = Empty of unit | Node of tree * int * tree;;
let rec size a = match a with
 | Empty() -> 0
 | Node (left, _, right) -> 1 + size left + size right ;;

size (Node(Empty(), 3, Node (Empty(), 4, Empty())));;

New data types

```
New data types

    recursive types

  # type tree = Empty of unit | Node of tree * int * tree;;
  # let rec size a = match a with
    | Empty() -> 0
    Node (left, _, right) -> 1 + size left + size right ;;
  # size (Node(Empty(), 3, Node (Empty(), 4, Empty())));;

    recursive polymorphic types

  # type 'a tree = Empty of unit | Node of 'a tree * 'a * 'a tree ;;
  # let rec size a = match a with
    | Empty() -> 0
    Node (left, _, right) -> 1 + size left + size right ;;
  # let a = Node(Empty(), 3, Node (Empty(), 4, Empty()));;
  # let b = Node(Empty(), "nihao", Node (Empty(), "bushi", Empty()));;
  # size b;;
  -: int = 2
  # size a;;
  -: int = 2
```

```
    recursive types

 # type tree = Empty of unit | Node of tree * int * tree;;
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 # let rec size a = match a with
   | Empty() -> 0
   Node (left, _, right) -> 1 + size left + size right ;;
     val size : tree -> int = <fun>
 # size (Node(Empty(), 3, Node (Empty(), 4, Empty())));;
 -: int = 2

    recursive polymorphic types

 # type 'a tree = Empty of unit | Node of 'a tree * 'a * 'a tree ;;
 type 'a tree = Empty of unit | Node of 'a tree * 'a * 'a tree
 # let rec size a = match a with
   | Empty() -> 0
   Node (left, _, right) -> 1 + size left + size right ;;
     val size : 'a tree -> int = <fun>
 # let a = Node(Empty(), 3, Node (Empty(), 4, Empty()));;
 val a : int tree = Node (Empty (), 3, Node (Empty (), 4, Empty ()))
 # let b = Node(Empty(), "nihao", Node (Empty(), "bushi", Empty()));;
 val b : string tree =
   Node (Empty (), "nihao", Node (Empty (), "bushi", Empty ()))
 # size b;;
 -: int = 2
 # size a;;
 -: int = 2
```

```
• recursive polymorphic types (alternative definition for binary trees)
# type 'a tree = Leaf of 'a | Node of 'a tree * 'a * 'a tree ;;
# let rec flatten a = match a with
        Leaf (x) -> [ x ]
        Node (tleft, _ , tright) -> List.append (flatten tleft) (flatten tright) ;;
# let a = Node ( Leaf (3), 5, Node (Leaf (4), 7, Leaf (6))) ;;
# flatten a ;;
# let rec flatten a = match a with
        Leaf (x) -> [ x ]
        Node (tleft, _ , tright) -> (flatten tleft) @ (flatten tright) ;;
```

New data types

• recursive polymorphic types (alternative definition for binary trees)

Caring about space

```
· with an extra argument as an accumulator of the result
```

Caring about space

· with an extra argument as an accumulator of the result





Naive algorithm

- 1) choose an unvisited pixel
- 2) traverse all similar connected pixels
- 3) and restart until all pixel are visited

Very high complexity:

- how to find an unvisited pixel ?
- how organizing exploration of connected pixels (which direction?)



Algorithm

1) first pass

- scan pixels left-to-right, top-to-bottom giving a new object id each time a new object is met

2) second pass

- generate equivalences between ids due to new adjacent relations met during scan of pixels.

3) third pass

- compute the number of equivalence classes

Complexity:

- scan twice full image (linear cost)
- try to efficiently manage equivalence classes (Union-Find by Tarjan)



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Exercise for next class

• find an algorithm for the labeling algorithm



Equivalence classes

"Union-Find"

- objects x_1, x_2, \ldots, x_n
- equivalences
- find the equivalence class of x_p
- 3 operations:
 - NEW(x) new object
- FIND(x) find canonical representative
- UNION(x, y)merge 2 equivalence classes













Exercice for next class

- find good primitives for graphics in Ocaml library
- design the overall structure of the labeling program