## Concurrency 4

CCS - Simulation and bisimulation. Coinduction.

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OutlineSolution to exercises from previous timeModern definition of CCS (1999)

- Syntax
- Labeled transition SystemSimulation and bisimulation
- Simulation
- Bisimulation
- Proof methods
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- Alternative characterization of bisimulation
- Bisimulation in CCS is a congruenceExercises


## Announcement

The class of Wednesday 26 October will follow the usual schedule (16h15-19h15).

## The semaphore

## Define in CCS a semaphore with initial value $n$

## First Solution

$$
\operatorname{rec}_{S_{n}} \text { down.rec }_{S_{n-1}}\left(\text { up. } S_{n}+\text { down.rec }_{S_{n-2}}\left(\ldots\left(\text { up. } S_{2}+\text { down.rec }_{S_{0}} \text { up. } S_{1}\right) \ldots\right)\right)
$$

## Second solution

- Let $S=\operatorname{rec}_{X}$ down.up. $X$
- Then $S_{n}=S|S| \ldots \mid S \quad n$ times


## Maximal trace equivalence is not a congruence

Consider the following processes

- $P=a .(b .0+c .0)$
- $Q=$ a.b. $0+$ a.c. 0
- $R=\bar{a} \cdot \bar{b} \cdot \bar{d} \cdot 0$
$P$ and $Q$ have the same maximal traces, but $(\nu a)(\nu b)(\nu c)(P \mid R)$ and $(\nu a)(\nu b)(\nu c)(Q \mid R)$ have different maximal traces.


## Solution to exercises from previous time Modern definition of CCS (1999) Simulation and bisimulation Exercises <br> Labeled transition System <br> Labeled transition system for "modern" CCS

We assume a given set of definitions $D$

$$
\begin{aligned}
& \text { [Act] } \underset{\mu . P \xrightarrow{\mu} P}{ } \quad[\operatorname{Res}] \frac{P \xrightarrow{\mu} P^{\prime} \quad \mu \neq a, \bar{a}}{(\nu a) P^{\mu}(\nu a) P^{\prime}} \\
& \text { [Sum1] } \frac{P \xrightarrow{\mu} P^{\prime}}{P+Q \xrightarrow{\stackrel{H}{\longrightarrow}} P^{\prime}} \\
& \text { [Sum2] } \frac{Q \xrightarrow{\mu} Q^{\prime}}{P+Q \xrightarrow{\mu} Q^{\prime}} \\
& {[\mathrm{Par1}] \frac{P \xrightarrow{\mu} P^{\prime}}{P\left|Q \xrightarrow{\mu} P^{\prime}\right| Q}} \\
& {[P a r 2] \frac{Q \stackrel{\mu}{\rightrightarrows} Q^{\prime}}{P|Q \xrightarrow{\mu} P| Q^{\prime}}} \\
& {\left[\text { Com] } \frac{P \xrightarrow{a} P^{\prime} Q \xrightarrow{\bar{a}} Q^{\prime}}{P\left|Q \xrightarrow{\tau} P^{\prime}\right| Q^{\prime}}\right.} \\
& {[R e c] \frac{P[\vec{a} / \vec{x}] \xrightarrow{\mu} P^{\prime} K(\vec{x}) \stackrel{\text { def }}{\stackrel{\text { den }}{ }} P \in D}{K(\vec{a}) \xrightarrow{\mu} P^{\prime}}}
\end{aligned}
$$

The reason for moving to "modern" CCS was to get static scope (thanks to the presence of the parameters). The old version had dynamic scope.

Modern definition of CCS (1999)

## Syntax of "modern" CCS

(channel, port) names: a, b, c, ...

- co-names: $\bar{a}, \bar{b}, \bar{c}, \ldots \quad$ Note: $\quad \overline{\bar{a}}=a$
- silent action:
- actions, prefixes: $\mu::=a|\bar{a}| \tau$
- processes: $P, Q \quad::=0 \quad$ inaction
u.P prefix
$P \quad Q$ paralle
$P+Q \quad$ (external) choice
$(\nu a) P$ restriction
$K(\vec{a}) \quad$ process name with parameters
- Process definitions:
$D \quad:: K(\vec{x}) \stackrel{\text { def }}{=} P \quad$ where P may contain only the $\vec{x}$ as channel names

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Simulation
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## Simulation

Definition We say that a relation R on processes is a simulation if

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P\mathcal{R}Q implies that if P }\xrightarrow{}{\mu}\mp@subsup{P}{}{\prime}\mathrm{ then }\exists\mp@subsup{Q}{}{\prime}\mathrm{ s.t. }Q\xrightarrow{}{\mu}\mp@subsup{Q}{}{\prime}\mathrm{ and }\mp@subsup{P}{}{\prime}\mathcal{R}\mp@subsup{Q}{}{\prime
```

- Note that this property does not uniquely defines $\mathcal{R}$. There may be several relations that satisfy it.
- Define $\lesssim=\bigcup\{\mathcal{R} \mid \mathcal{R}$ is a simulation $\}$
- Theorem $\lesssim$ is a bisimulation (Proof: Exercise)
- $P \lesssim Q$ intuitively means that $Q$ can do everything that $P$ can do. $Q$ simulates $P$.


## Bisimulation

## Proof methods

- Definition We say that a relation $R$ on processes is a bisimulation if

$$
\begin{aligned}
& P \mathcal{R} Q \text { implies that if } P \xrightarrow{\mu} P^{\prime} \text { then } \exists Q^{\prime} \text { s.t. } Q \xrightarrow{\mu} Q^{\prime} \text { and } P^{\prime} \mathcal{R} Q^{\prime} \\
& \text { if } Q \xrightarrow{\mu} Q^{\prime} \text { then } \exists P^{\prime} \text { s.t. } P \xrightarrow{\mu} P^{\prime} \text { and } P^{\prime} \mathcal{R} Q^{\prime}
\end{aligned}
$$

- Again, this property does not uniquely defines $\mathcal{R}$. There may be several relations that satisfy it.
- Define $\sim=\bigcup\{\mathcal{R} \mid \mathcal{R}$ is a bisimulation $\}$
- Theorem $\sim$ is a bisimulation (Proof: Exercise)
- $P \sim Q$ intuitively means that $Q$ can do everything that $P$ can do, and viceversa at every step of the computation. $Q$ is bisimilar to $P$.


## Examples and exercises

## Examples and exercises

- Consider the following processes
- $P=a .(b .0+c .0)$
- $Q=$ a.b. $0+$ a.c. 0

Prove that $Q \lesssim P$ but $P \not \subset Q$ and $Q \nsim P$

- Assume that $Q \lesssim P$ and $P \lesssim Q$ (for two generic $P$ and $Q$ ). Does it follow that $P \sim Q$ ?
- Consider the following processes
- $R=a .(b .0+b .0)$
- $S=$ a.b. $0+$ a.b. 0

Prove that $Q \sim P$

- Consider the two definitions of semaphore given at the beginning of this lecture. Prove that they are bisimilar.
- Consider the processes $H(a)$ and $K(a)$ defined by $H(x) \stackrel{\text { def }}{=} x \cdot H(x)$ and $K(x) \stackrel{\text { def }}{=} x . K(x) \mid x . K(x)$. Are they bisimilar?
- What is the smallest bisimulation?
- Simulation and bisimulation are coinductive definitions
- In order to prove that $P \lesssim Q$ it is sufficient to find a simulation $\mathcal{R}$ such that $P \mathcal{R} Q$
- Similarly, in order to prove that $P \sim Q$ it is sufficient to find a bisimulation $\mathcal{R}$ such that $P \mathcal{R} Q$

| Solution to exercises from previous time | Modern definition of $\operatorname{CCS}(1999)$ <br> $\circ 0$ | Simulation and bisimulation <br> $0000 \bullet$ <br> Alternative characterization of bisimulation |
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| Bisimulation as greatest fixpoint |  |  |

- Consider the set of relations on processes (that is, on the powerset of the cartesian product on processes) ordered by set inclusion. Obviously, this is a complete lattice.
- Definition Let $\mathcal{F}$ be a function on relation defined in the following way:

$$
\begin{array}{lll}
P \mathcal{F}(\mathcal{R}) Q & \text { iff } & \text { if } P \xrightarrow{\mu} P^{\prime} \text { then } \exists Q^{\prime} \text { s.t. } Q \xrightarrow{\mu} Q^{\prime} \text { and } P^{\prime} \mathcal{R} Q^{\prime} \\
& \text { if } Q \xrightarrow{\mu} Q^{\prime} \text { then } \exists P^{\prime} \text { s.t. } P \xrightarrow{\mu} P^{\prime} \text { and } P^{\prime} \mathcal{R} Q^{\prime}
\end{array}
$$

- Lemma $\mathcal{F}$ is monotonic
- Theorem (Knaster-Tarski) F has (unique) least and greatest fixpoints, and

$$
\begin{aligned}
\operatorname{lfp}(\mathcal{F}) & =\bigcap\{\mathcal{R} \mid \mathcal{F}(\mathcal{R}) \subseteq \mathcal{R}\} \\
\operatorname{gfp}(\mathcal{F}) & =\bigcup\{\mathcal{R} \mid \mathcal{R} \subseteq \mathcal{F}(\mathcal{R})\}
\end{aligned}
$$

- Corollary $\sim=\operatorname{gfp}(\mathcal{F})$
- A similar characterization, of course, holds for $\lesssim$ as well.


## Bisimulation in CCS is a congruence

- Definition A relation R on a language is called congruence if
- $\mathcal{R}$ is an equivalence relation (i.e. it is reflexive, symmetric, and transitive), and
- $\mathcal{R}$ is preserved by all the operators of the language, namely if $P \mathcal{R} Q$ then op $(P, \vec{R}) \mathcal{R}$ op $(P, \vec{R})$
- Theorem $\sim$ is a congruence relation


## Exercises

- Complete the proof that bisimulation in CCS is a congruence
- Prove that if $P \lesssim Q$ then the traces of $P$ are contained in the traces of $Q$
- Prove that if $P \sim Q$ then $P \lesssim Q$ and $Q \lesssim P$
- Prove that
- $P+0 \sim P$ and $P \mid 0 \sim P$
- $P+P \sim P$ but (in general) $P \mid P \nsim P$
- $P+Q \sim Q+P$ and $P|Q \sim Q| P$
- $(P+Q)+R \sim P+(Q+R)$ and $(P \mid Q)|R \sim P|(Q \mid R)$

